

Dialects in LLVM IR

An Example using Cooperative Matrices

Cooperative Matrices

- AI applications require lots of matrix-matrix multiplications
- New Vulkan shader extension introduces the cooperative matrix type
- Special data layout depending on hardware support
- Some requirements on AMD GPUs:
 - When calculating $A \cdot B + C$, A needs to be transposed

Transpose as high-level operation

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5     %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6     ret <8 x float> %a.t  
7 }
```

```
...  
958 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
959     %1 = call i32 @llvm.amdgcn.mbcnt.lo(i32 -1, i32 0)  
960     %2 = call i32 @llvm.amdgcn.mbcnt.hi(i32 -1, i32 %1)  
961     %3 = and i32 %2, 1  
962     %4 = icmp eq i32 %3, 0  
963     %5 = extractelement <8 x float> %a, i64 0  
964     %6 = bitcast float %5 to i32  
965     %7 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %6, i32 14570689)  
966     %8 = bitcast i32 %7 to float  
967     %9 = extractelement <8 x float> %a, i64 1  
968     %10 = bitcast float %9 to i32  
969     %11 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %10, i32 14570689)  
970     %12 = bitcast i32 %11 to float  
971     %13 = extractelement <8 x float> %a, i64 2  
972     %14 = bitcast float %13 to i32  
973     %15 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %14, i32 14570689)  
974     %16 = bitcast i32 %15 to float  
975     %17 = extractelement <8 x float> %a, i64 3  
976     %18 = bitcast float %17 to i32  
977     %19 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %18, i32 14570689)  
978     %20 = bitcast i32 %19 to float  
979     %21 = extractelement <8 x float> %a, i64 4  
980     %22 = bitcast float %21 to i32  
981     %23 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %22, i32 14570689)  
982     %24 = bitcast i32 %23 to float  
983     %25 = extractelement <8 x float> %a, i64 5  
984     %26 = bitcast float %25 to i32  
985     %27 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %26, i32 14570689)  
986     %28 = bitcast i32 %27 to float  
987     %29 = extractelement <8 x float> %a, i64 6  
988     %30 = bitcast float %29 to i32  
989     %31 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %30, i32 14570689)  
990     %32 = bitcast i32 %31 to float  
991     %33 = extractelement <8 x float> %a, i64 7  
992     %34 = bitcast float %33 to i32  
993     %35 = call i32 @llvm.amdgcn.mov.dpp8.i32(i32 %34, i32 14570689)  
994     %36 = bitcast i32 %35 to float  
...
```


Working with new intrinsics – current approach

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

Working with new intrinsics – current approach

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5     %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6     ret <8 x float> %a.t  
7 }
```

```
const static char CooperativeMatrixTranspose[] = "lgc.cooperative.matrix.transpose";
```

Working with new intrinsics – current approach

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
const static char CooperativeMatrixTranspose[] = "lgc.cooperative.matrix.transpose";
```

```
std::string callName(s: lgcName::CooperativeMatrixTranspose);
```

```
Value *args[] = {[0]=matrix, [1]=elementType, [2]=layout};
```

```
CallInst *result = CreateNamedCall(funcName: callName, retTy: matrix->getType(),  
args, attribs: {[0]=Attribute::ReadOnly, [1]=Attribute::WillReturn});
```


Working with new intrinsics – current approach

```
const static char CooperativeMatrixTranspose[] = "lgc.cooperative.matrix.transpose";

std::string callName(s: lgcName::CooperativeMatrixTranspose);
Value *args[] = {[0]=matrix, [1]=elementType, [2]=layout};

CallInst *result = CreateNamedCall(funcName: callName, retTy: matrix->getType(),
                                   args, attrs: {[0]=Attribute::ReadOnly, [1]=Attribute::WillReturn});

if (auto *call: CallInst * = dyn_cast<CallInst>(Val: input)) {
    if (auto *callee: Function * = call->getCalledFunction()) {
        if (callee->getName().starts_with(Prefix: lgcName::CooperativeMatrixTranspose)) {
            Value *src = call->getArgOperand(i: 0);
        }
    }
}
```

Working with new intrinsics – current approach

```
const static char CooperativeMatrixTranspose[] = "lgc.cooperative.matrix.transpose";

std::string callName(s: lgcName::CooperativeMatrixTranspose);
Value *args[] = {[0]=matrix, [1]=elementType, [2]=layout};

CallInst *result = CreateNamedCall(funcName: callName, retTy: matrix->getType(),
                                   args, attrs: {[0]=Attribute::ReadOnly, [1]=Attribute::WillReturn});

if (auto *call: CallInst * = dyn_cast<CallInst>(Val: input)) {
    if (auto *callee: Function * = call->getCalledFunction()) {
        if (callee->getName().starts_with(Prefix: lgcName::CooperativeMatrixTranspose)) {
            Value *src = call->getArgOperand(i: 0);
        }
    }
}
```

Problems

- New intrinsics are all CallInst
 - Common pattern: iterate over instructions, cast to CallInst, compare name string
 - Accessing arguments with an index
- Not developer-friendly

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5     %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6     ret <8 x float> %a.t  
7 }
```

```
def LgcCmDialect : Dialect {  
    let name = "lgc.cooperative.matrix";  
    let cppNamespace = "lgc::cooperativeMatrix";  
}
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5     %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6     ret <8 x float> %a.t  
7 }
```

```
def LgcCmDialect : Dialect {  
    let name = "lgc.cooperative.matrix";  
    let cppNamespace = "lgc::cooperativeMatrix";  
}
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def LgcCmDialect : Dialect {  
  let name = "lgc.cooperative.matrix";  
  let cppNamespace = "lgc::cooperativeMatrix";  
}
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def LgcCmDialect : Dialect {  
  let name = "lgc.cooperative.matrix";  
  let cppNamespace = "lgc::cooperativeMatrix";  
}
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [Memory<[(read)]>, WillReturn]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);  
  
  let summary = "transpose a matrix";  
  let description = [{  
    Given a cooperative matrix, the element type and the matrix layout, returns  
    the transposed matrix.  
  }];  
}
```


Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)
6   ret <8 x float> %a.t
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {
```

```
CallInst *result = CreateNamedCall(funcName: callName, retTy: matrix->getType(),
    args, attrs: {[0]=Attribute::ReadOnly, [1]=Attribute::WillReturn});
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [Memory<[(read)]>, WillReturn]> {  
  let arguments = (ins [FixedVectorType $element_type, $num_elements]:$matrix, I32 $elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32 $elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [Memory<[(read)]>, WillReturn]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32 $elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);
```

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {  
5     %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6     ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {  
    let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
    let results = (outs (eq $matrix):$result);
```

Solution: llvm-dialects

```
4 define <8 x float> @test transpose_simple(<8 x float> %a) {  
5   %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)  
6   ret <8 x float> %a.t  
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
  let results = (outs (eq $matrix)$result);
```

Many other constraints possible, see the [Constraints.md](#) in the [llvm-dialects repo](#)

Solution: llvm-dialects

```
4 define <8 x float> @test_transpose_simple(<8 x float> %a) {
5     %a.t = call <8 x float> @lgc.cooperative.matrix.transpose.v8f32(<8 x float> %a, i32 1, i32 0)
6     ret <8 x float> %a.t
7 }
```

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {
    let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);
    let results = (outs (eq $matrix):$result);

    let summary = "transpose a matrix";
    let description = [{
        Given a cooperative matrix, the element type and the matrix layout, returns
        the transposed matrix.
    }];
}
```

Solution: llvm-dialects

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);
```

Solution: llvm-dialects

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);  
  
  CoopMatrixTransposeOp *result = create<CoopMatrixTransposeOp>(  
    matrix, elementType, layout);  
  
  std::string callName(s: lgcName::CooperativeMatrixTranspose);  
  Value *args[] = {[0]=matrix, [1]=elementType, [2]=layout};  
  
  CallInst *result = CreateNamedCall(funcName: callName, retTy: matrix->getType(),  
    args, attribs: {[0]=Attribute::ReadOnly, [1]=Attribute::WillReturn});
```

Solution: llvm-dialects

```
def CoopMatrixTransposeOp : Op<LgcCmDialect, "transpose", [[Memory<[(read)]>, WillReturn]]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);  
  
  if (isa<cooperativeMatrix::CoopMatrixTransposeOp>(Val: input)) {  
  
    if (auto *call: CallInst * = dyn_cast<CallInst>(Val: input)) {  
      if (auto *callee: Function * = call->getCalledFunction()) {  
        if (callee->getName().starts_with(Prefix: lgcName::CooperativeMatrixTranspose)) {  
          Value *src = call->getArgOperand(i: 0);  
        }  
      }  
    }  
  }  
}
```

Solution: llvm-dialects

```
CoopMatrixTransposeOp *result = create<CoopMatrixTransposeOp>(
    matrix, elementType, layout);
```

```
static const auto visitor = You, 12 hours ago • Uncommitted changes
    llvm_dialects::VisitorBuilder<LowerCooperativeMatrix>()
        .add(fn: &LowerCooperativeMatrix::visitCooperativeMatrixTranspose)
        .build();

visitor.visit(&payload: *this, &: module);
```

```
void LowerCooperativeMatrix::visitCooperativeMatrixTranspose(
    cooperativeMatrix::CoopMatrixTransposeOp &coopTranspose) {
```

Solution: llvm-dialects

```
def CoopMatrixTransposeOp : LgcCmOp<"transpose", [Memory<[(read)]>, WillReturn]> {  
  let arguments = (ins (FixedVectorType $element_type, $num_elements):$matrix, I32:$elem_type, I32:$layout);  
  let results = (outs (eq $matrix):$result);
```

Solution: llvm-dialects

```
|> {  
  I32:$elem_type, I32:$layout);
```

```
transpose.getElemType()  
transpose.getLayout()
```

```
transpose->getArgOperand(i: 1)  
transpose->getArgOperand(i: 2)
```

Additional features

- More complex constraints
- OpSet/OpMap working on classes of Operations
- ContextExtension

Future Work

- Custom Type Definitions
- Human readable structs in metadata

Thank you for listening!